Robustly Safe Compilation

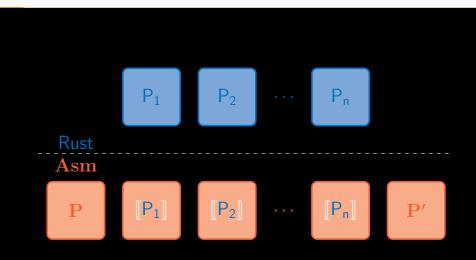


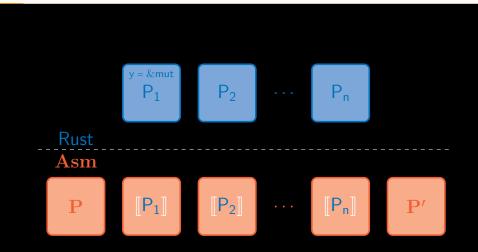
Marco Patrignani^{1,2} Deepak Garg³

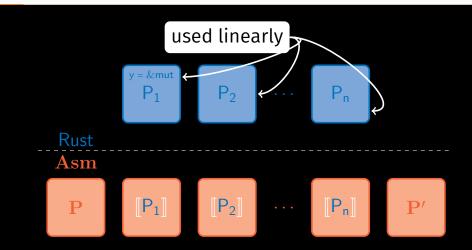


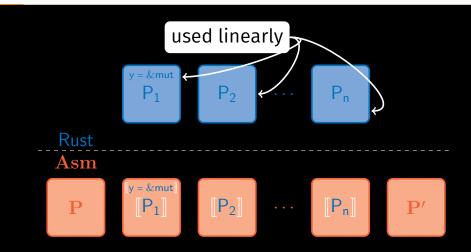
10th April 2019

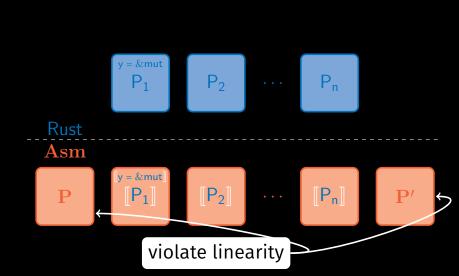


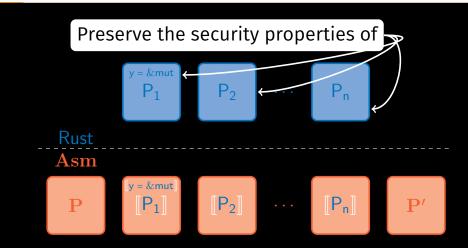


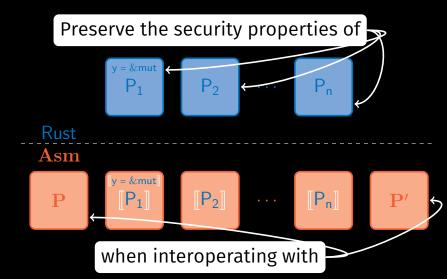


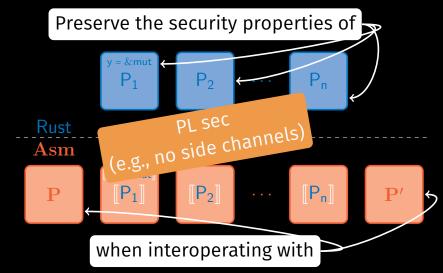


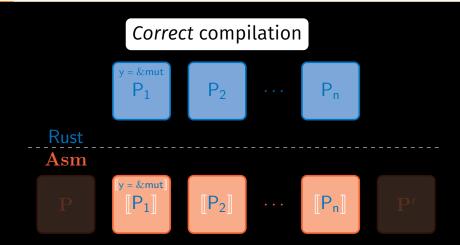


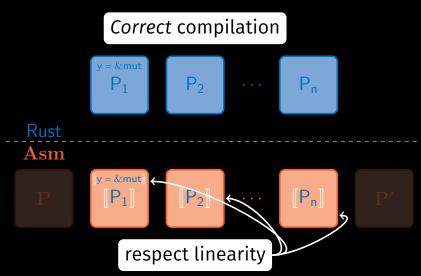


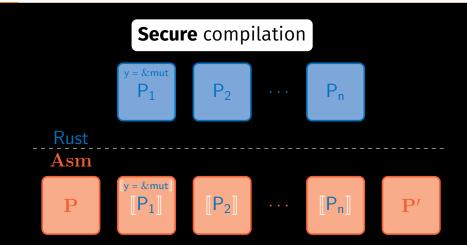


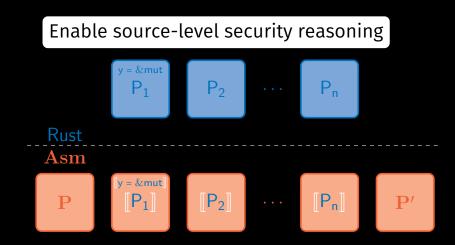




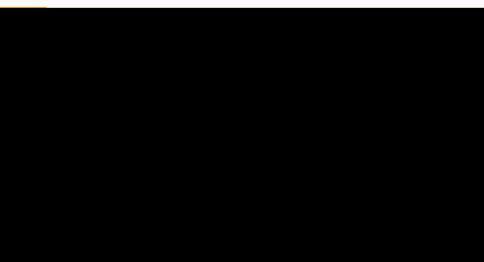








Do Secure Compilers Exist?



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Yes!

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Yes!

They rely on security mechanisms:

- enclaves
- capabilities
- types
- tagged memory

- ASLR
- CFI, SFI
- processes
- . . .

Some secure compilers:

• P1 : lack formal proof of their security guarantees

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- P3 : inefficient

complex secure compilers:

proof^s : lack formal proof of their security guarantees

- P2 : prove preservation of ad-hoc security properties
 P3 : inefficient
- **P3** : inefficient dictated by existing definitions



Define a formal criterion for secure compilation:

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- attainable
- efficient (wrt existing ones)
- easy not too hard to prove

Define a formal criterion for secure compilation:

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- efficient (wrt existing ones)
- easy not too hard to prove
- with clear security guarantees

• *RSC*: known criterion, meets our goals

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no runtime checks!

• two proof techniques for RSC

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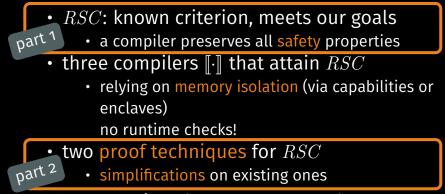
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- a comparison between *RSC* and *FAC*

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• a comparison between *RSC* and *FAC*

Talk Roadmap

Robust Safety

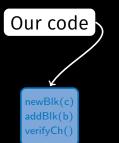
Robustly Safe Compilation

Backtranslation Proof Technique

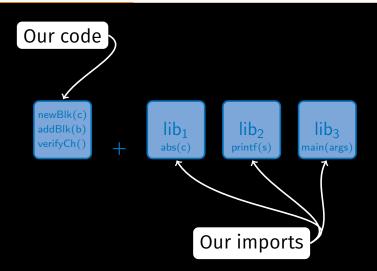
Robust Safety

- Robustness
- Behaviour
- Safety

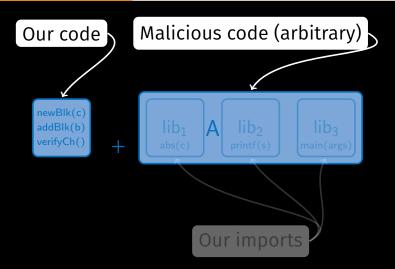
Robustness



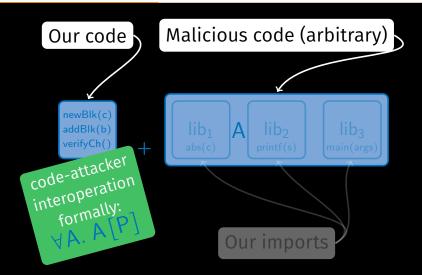
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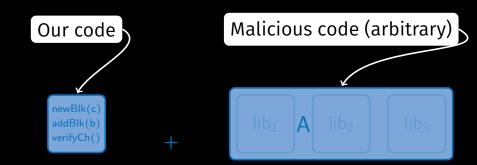


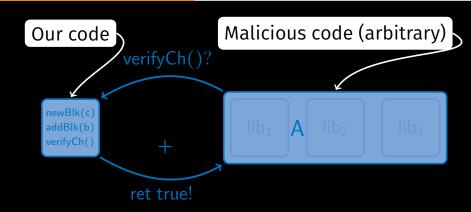
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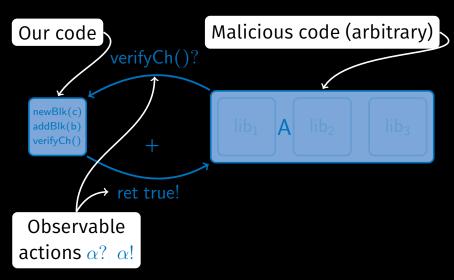


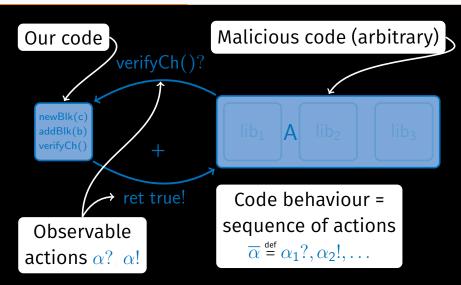
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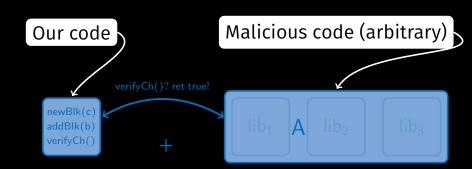




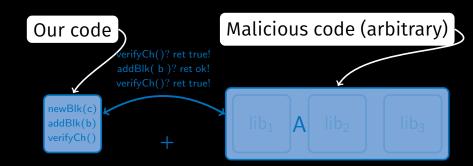




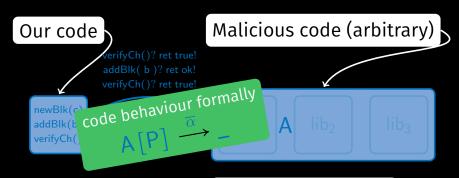




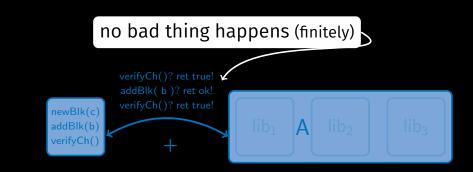
Code behaviour = sequence of actions $\overline{\alpha} \stackrel{\text{\tiny def}}{=} \alpha_1?, \alpha_2!, \dots$

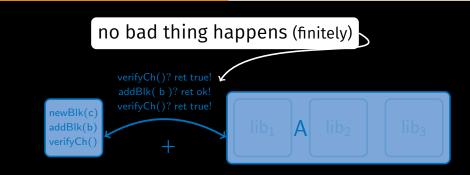


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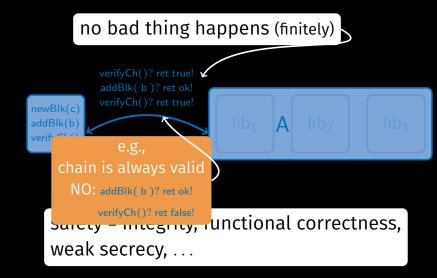


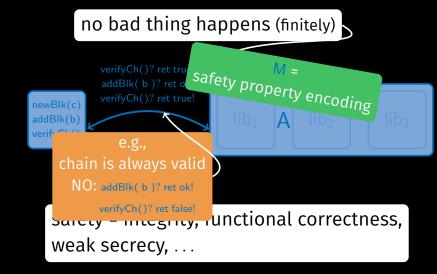
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safety = integrity, functional correctness, weak secrecy, ...





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- that respects that safety property (then $M \vdash \overline{\alpha}$)

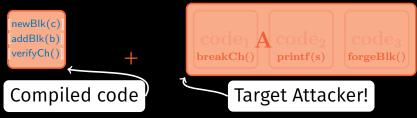
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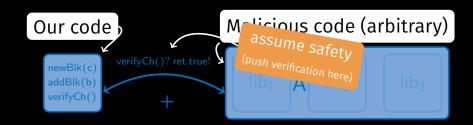


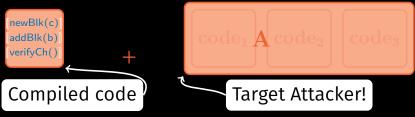
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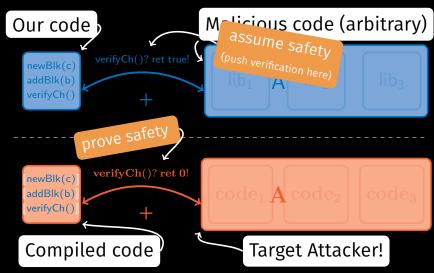


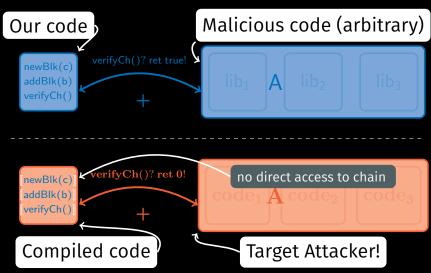


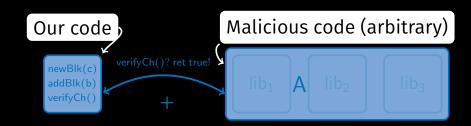


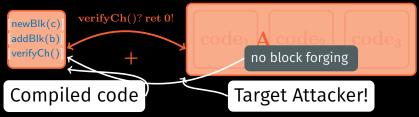


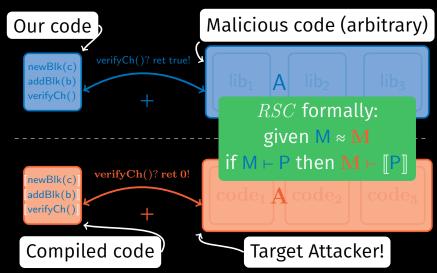












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(equivalence to be proven, generally true)

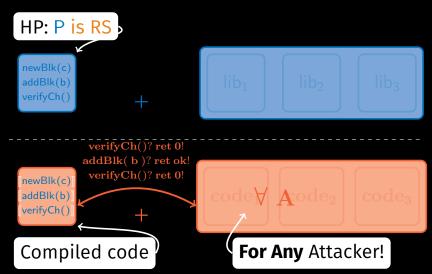
Backtranslation Proof Technique

Backtranslation: Build A From A or $\overline{\alpha}$

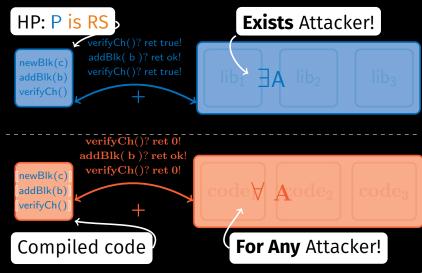




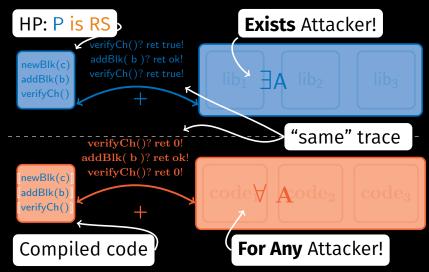
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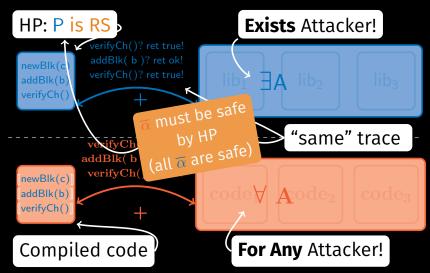
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- then $\overline{\alpha}$ is not bad

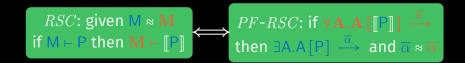
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- given any behaviour $(A[[P]] \xrightarrow{\overline{\alpha}})$
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 because a does not violate safety
 (by RS of P) (for a ≈ a)

- Safety = nothing bad happens
 so if it were to happen it would finitely
- given any behave
- if we can replica
- then $\overline{\alpha}$ is not ba then $\exists A.A[P] \xrightarrow{\alpha}$ and $\overline{\alpha} \approx \overline{\alpha}$ because $\overline{\alpha}$ does not violate safety (by RS of P) (for $\overline{\alpha} \approx \overline{\alpha}$)

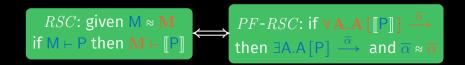
PF-RSC formally:

if $\forall A.A[[P]] \xrightarrow{\overline{\alpha}}$

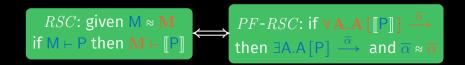
$$\begin{array}{c} RSC: \text{ given } \mathsf{M} \approx \mathbf{M} \\ \text{if } \mathsf{M} \vdash \mathsf{P} \text{ then } \mathbf{M} \vdash \llbracket \mathsf{P} \rrbracket \end{array} \longleftrightarrow \begin{array}{c} PF\text{-}RSC: \text{ if } \forall \mathbf{A}.\mathbf{A} \llbracket \mathsf{P} \rrbracket \rrbracket \xrightarrow{\overline{\alpha}} \\ \text{then } \exists \mathsf{A}.\mathsf{A} \llbracket \mathsf{P} \rrbracket \xrightarrow{\overline{\alpha}} \text{ and } \overline{\alpha} \approx \overline{\alpha} \end{array}$$



• \iff must be proven (when needed)



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- sanity-check for cross-language safety encoding (M ≈ M)

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- encode safety properties in the systems
- ensure the desired property follows from the encoding
- use our proof techniques to prove safety is preserved

What Else?

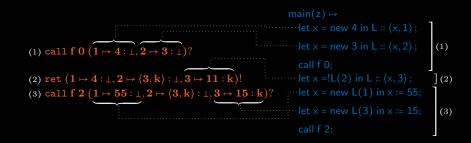
The paper (or the techreport) contains more:

- one $RSC \llbracket \cdot \rrbracket_{L^{\mathbf{P}}}^{\mathsf{L}^{\mathsf{U}}}$ from untyped while to capabilities
- one $RSC \llbracket \cdot \rrbracket_{L^{\pi}}^{L^{\pi}}$ from typed, concurrent while to capabilities
- one RSC $\llbracket \cdot \rrbracket_{L^{I}}^{L^{\tau}}$ from typed, concurrent while to *enclaves*
- a backtranslation-based RSC proof (for $[\cdot]_{L^{\mathbf{P}}}^{\mathsf{L}^{U}}$)
- two simulation-based RSC proofs (for $\llbracket \cdot \rrbracket_{\mathbf{L}^{\pi}}^{\mathbf{L}^{\tau}}$ and $\llbracket \cdot \rrbracket_{\mathbf{L}^{I}}^{\mathbf{L}^{\tau}}$
- a *FAC* $[]_{L^{P}}^{L^{U}}$ from untyped while to capabilities
- a backtranslation-based FAC proof sketch (for $\llbracket \cdot \rrbracket
 bracket{L^{P}}^{L^{U}}$)
- a comparison of efficiency and proof complexity between $[\![\cdot]\!]_{L^P}^{L^U}$ and $[\![\cdot]\!]_{L^P}^{L^U}$

Questions?



Backtranslation Example



Simulation-Based Proof

Set up cross-language relation \approx_{β} that:

- knows trusted locations: $\tau \not\vdash \circ$.
- splits heaps (source and target) into trusted and untrusted;
- constitutes trusted heap by trusted locations ($\tau \not\vdash \circ$);
- relates trusted heap to trusted heap
- protects every trusted location by a capability;
- capability protecting a trusted **location** is not in attacker code, nor in the untrusted heap